

"Beins"



①

- It is really important (mathematically and physically) to keep in mind that the spacetime manifold is while typically curved and lumpy — is locally flat spacetime.

(1.1a) let flat-type indices be $\{A\}$, $A = 0, 1, 2$ or 3
 (1.1b) & curved-type indices be $\{\alpha\}$, $\alpha = 0, 1, 2$ or 3

⊕ At each point, since spacetime is locally flat, we can write for (say) a $(1,0)$ tensor V

$$V^A = e^A_\mu V^\mu$$

invertible, 4^2 components
 "vierbein" in 4-d

Similarly:-
 $(0,1)$ tensors have flat components

$$\omega_A = e_A^\mu \omega_\mu$$

where

$$e_A^\mu e_B^\nu = \delta_A^B$$

&

$$e_A^\mu e_A^\nu = \delta^\mu_\nu$$

$\leftarrow = \eta_A^B$

$\leftarrow = g^\mu_\nu$

⊗ Flat indices are raised/lowered via η^{AB} & η_{CD} ;

⊗ curved indices are raised/lowered via $g^{\mu\nu}$ & $g_{\alpha\beta}$.

- Since g is a rank (0,2) tensor, we naturally write

$$g_{\mu\nu} = e^A_\mu e^B_\nu \eta_{AB}$$

Spin connection 1-form ω^A_B

- The Christoffel is not the only available connection allowing us to parallel-transport stuff around...! In particular, $\Gamma^{\mu}_{\nu\rho}$ does not provide for parallel-transport of SPINORS

↳ objects with spin $\frac{1}{2}$ ($2n+1$) \hbar , $n \in \mathbb{Z}^+$.

(e.g. electron!)

$$\omega^A_B = \omega^A_{B\mu} dx^\mu$$

⊗ Spin connection 1-form

(components in coordinate basis)

- [We set torsion to zero, so] the equation satisfied by ω^A_B is

$$\text{det} + \omega^A_B \wedge e^B = 0$$

↖ This is a 2-form equation because (e.g.) $e^B_\mu dx^\mu$ is a 1-form and $\omega^A_B = \omega^A_{B\mu} dx^\mu$ is a 1-form too.

- ⊕ The equation above is usually the quickest way to find ω^A_B ! 😊

- Spinors carry special representations of $SO(1,3)$, the Lorentz group.

For a spinor (with spinor components ψ^α), ω defines

$$\hat{\nabla}_\mu \psi = \left(\partial_\mu + \frac{1}{4} \omega_{AB\mu} \Gamma^{[AB]} \right) \psi$$

This is useful technology for those interested in particle theory and string theory!!

Riemann two-form R^A_B

- The spin connection is also useful because it leads directly to the Riemann two-form

(4.1)

$$R^A_B = d\omega^A_B + \omega^A_C \wedge \omega^C_B$$

We will have a lot more to say about Riemann in the coming weeks. For now, just treat this as a mathematical definition of an object whose physical significance we have yet to elucidate and understand... 😊

(4.2)

- Let's illustrate the power of the language of differential forms by doing an example of how to compute ∇_{Feynman} using our equation which has best friend (4.3), i.e.

$$R^A_B = d\omega^A_B + \omega^A_C \wedge \omega^C_B$$
 "Cartan structure equations"

(4.3)

- Let's do the example $ds^2 = -c^2 dt^2 + a^2(t) |d\vec{x}|^2$
 - In (4.3), all spatial distances scaled by $a(t)$ → "SCALE FACTOR"

$$(5.1) \quad \text{Basic eqn: } g_{\mu\nu} = e^A_\mu e^B_\nu \eta_{AB} \quad \text{.}$$

(5)

Of course, the choice of 'beins' is not unique...
So let's pick really simply.

$$(5.2a) \quad \text{Define} \\ \text{and}$$

$$e^{\hat{0}}_0 = c$$

$$e^{\hat{i}}_j = a(t) \delta^i_j$$

Then we easily reproduce (5.1) 😊

⊗ Now look at $de^A + \omega^A_B \wedge e^B = 0$.

$$\text{First step: form } e^{\hat{0}}_0 = e^{\hat{0}}_\alpha dx^\alpha = c dt \\ \text{and } e^{\hat{i}}_j = e^{\hat{i}}_\alpha dx^\alpha = a(t) dx^i$$

$$\text{Then } de^{\hat{0}} = d(c dt) \stackrel{!}{=} 0 \\ = -\omega^{\hat{0}}_{\hat{0}} \wedge e^{\hat{0}} - \omega^{\hat{0}}_{\hat{i}} \wedge e^{\hat{i}}$$

Now we need to know a useful property of ω^A_B :

$$\omega_{AB} = \omega_{[AB]}$$

⑥

Then, using $\eta_{\hat{A}\hat{B}}$ to raise, etc, we have

$$\omega_{\hat{\alpha}\hat{\beta}} = \omega_{\hat{\alpha}\hat{\gamma}} \eta_{\hat{\gamma}\hat{\beta}} + 0 = -\omega_{\hat{\beta}\hat{\alpha}} = 0 \text{ by antisymmetry.}$$

$$\text{Also, } \omega_{\hat{t}\hat{t}} = \eta_{\hat{\alpha}\hat{\alpha}} \omega_{\hat{\alpha}\hat{t}} = -\eta_{\hat{\alpha}\hat{\alpha}} \omega_{\hat{t}\hat{\alpha}} = -\omega_{\hat{t}\hat{\alpha}} \quad (1)$$

$$\text{So } d\omega_{\hat{t}\hat{t}} = 0 \Rightarrow \omega_{\hat{t}\hat{t}} \wedge e_{\hat{t}} = 0$$

$$\text{but } e_{\hat{t}} = \alpha(t) dx^i \Rightarrow \omega_{\hat{t}\hat{t}} = \alpha(t) e_{\hat{t}} \quad \exists \alpha(t) \quad \leftarrow \text{(we'll find this shortly)}$$

• Spatial eqns? Have

$$\begin{aligned} d e_{\hat{t}} &= d(\alpha(t) dx^i) \\ &= \dot{\alpha} dt \wedge dx^i = \left(\frac{1}{c} \frac{\dot{a}}{a}\right) e_{\hat{t}} \wedge e_{\hat{t}} \\ &= -\omega_{\hat{t}\hat{\alpha}} \wedge e_{\hat{\alpha}} - \omega_{\hat{t}\hat{k}} \wedge e_{\hat{k}} \end{aligned}$$

$$\Rightarrow +\omega_{\hat{\alpha}\hat{t}} \wedge e_{\hat{\alpha}} = \left(\frac{1}{c} \frac{\dot{a}}{a}\right) e_{\hat{t}} \wedge e_{\hat{\alpha}}$$

i.e.

$$\omega_{\hat{\alpha}\hat{t}} = \frac{1}{c} \frac{\dot{a}}{a} e_{\hat{t}}$$

☺
Q.E.D.

For our last trick, let's find Riemann.

Starting from our choice $\begin{cases} e_{\hat{0}}^i = c dt \\ e_{\hat{1}}^i = a(t) dx^i \end{cases}$

we got

$$\begin{cases} \omega_{\hat{0}\hat{0}} \equiv 0 \\ \omega_{\hat{0}\hat{1}} = -\omega_{\hat{1}\hat{0}} = -\frac{1}{c} \frac{\dot{a}}{a} e_{\hat{1}}^i \\ \omega_{\hat{1}\hat{1}} = 0 \end{cases}$$

$\Rightarrow R_{\hat{0}\hat{1}}^{\hat{0}\hat{1}} = \omega_{\hat{1}\hat{1}} \wedge \omega_{\hat{0}\hat{0}} = 0$ by antisymmetry of $\omega_{\hat{A}\hat{B}}$ & of \wedge
by property of ω & of \wedge

Also, $R_{\hat{1}\hat{1}}^{\hat{0}\hat{0}} = d\omega_{\hat{0}\hat{1}}^{\hat{0}\hat{0}} + \omega_{\hat{0}\hat{1}}^{\hat{0}\hat{0}} \wedge \omega_{\hat{1}\hat{1}}^{\hat{0}\hat{0}} = d\left(\frac{1}{c} \frac{\dot{a}}{a} dx^i\right) = \frac{1}{c} \ddot{a} dt \wedge dx^i = \frac{1}{c^2} \frac{\ddot{a}}{a} e_{\hat{0}}^0 \wedge e_{\hat{1}}^i$

Then $R_{\hat{1}\hat{0}}^{\hat{1}\hat{0}} = \frac{1}{c^2} \frac{\ddot{a}}{a} e_{\hat{0}}^0 \wedge e_{\hat{1}}^i$

Lastly, $R_{\hat{1}\hat{1}}^{\hat{1}\hat{1}} = \omega_{\hat{0}\hat{1}}^{\hat{1}\hat{1}} \wedge \omega_{\hat{1}\hat{1}}^{\hat{1}\hat{1}} = -\frac{1}{c^2} \left(\frac{\dot{a}}{a}\right)^2 e_{\hat{1}}^i \wedge e_{\hat{1}}^j$

$$\Rightarrow R_{\hat{0}\hat{1}}^{\hat{0}\hat{1}} = \frac{\ddot{a}}{a} \delta_{ij}^{\hat{0}\hat{1}}$$

$$R_{\hat{0}\hat{0}}^{\hat{1}\hat{1}} = \frac{\ddot{a}}{a} \delta_{ij}^{\hat{1}\hat{1}}$$

$$R_{\hat{1}\hat{1}}^{\hat{1}\hat{1}} = \left(\frac{\dot{a}}{a}\right)^2 (\delta_{ij}^{\hat{1}\hat{1}} \delta_{kl}^{\hat{1}\hat{1}} - \delta_{ij}^{\hat{1}\hat{1}} \delta_{kl}^{\hat{1}\hat{1}})$$

• Full contraction: $R_{\hat{A}\hat{B}\hat{A}\hat{B}} = 2(d-1) \frac{\ddot{a}}{a} + (d-1)(d-2) \left(\frac{\dot{a}}{a}\right)^2$

• Singular where $a(t) \rightarrow 0$ (or \ddot{a} or $\dot{a} \rightarrow \infty$) "Big Bang/Crunch".