

Last time, we studied

- momentum 4-vector
- constant acceleration
- the Equivalence Principle

and introduced

- spacetime as a manifold
- metric tensor.

①

Today :-

- Vectors (again)
- Commutator of vectors
- Tensors (again)
- Metric: canonical form, locally inertial coords
- Causality
- ϵ tensor density

Vectors (again)

Now we can have arbitrary functions on our manifold. For some function $f(x^M)$, we have for $x^M(\lambda)$

$$\frac{df}{d\lambda} = \frac{\partial f}{\partial x^M} \frac{dx^M}{d\lambda}$$

← directional derivative of f (along λ -direction)

$$(1.1) \quad \text{or} \quad \frac{d}{d\lambda} = \frac{dx^M}{d\lambda} \partial_\mu$$

i.e. $\{\hat{e}_{(\mu)} = \partial_\mu\}$ is a set of basis vectors.

- The tangent space $T_p(M)$ at some point p can actually be thought of as the space of derivatives in this way(!). It is a vector space ... and the Leibniz rule is obeyed.

- Commutator of 2 vector fields :

$$[X, Y](f) = X(Y(f)) - Y(X(f))$$

In components,

$$(1.2) \quad [X, Y]^M = X^\lambda \partial_\lambda Y^M - Y^\lambda \partial_\lambda X^M$$

→ linear
→ obeys Leibniz rule

Example of vector field: wind at surface of Earth.
 (Math: always have (at least) 2 zeroes on S^2 ... :))

Tensors (again)

As before, but this time $\frac{\partial x^{\mu'}}{\partial x^{\nu}}$ \neq constant matrix

Metric tensor non-flat space

(2.1)

$g_{\mu\nu}$

our length-measurer, now depends on x^{λ} i.e. where you are in space-time.

(2.2)

"Line element"

$ds^2 = g_{\mu\nu} dx^{\mu} dx^{\nu}$

(ds^2 invariant under coord changes)

- $g_{\mu\nu}$ is symmetric
- inverse metric is denoted $g^{\mu\nu}$

and

(2.3)

$g^{\mu\nu} g_{\nu\lambda} = g^{\mu}_{\lambda} = \delta^{\mu}_{\lambda}$

↑ Kronecker delta

• g is used to raise and lower indices on tensors

eg. Euclidean \mathbb{R}^3 : $ds^2 = dx^2 + dy^2 + dz^2$ Cartesian
 $ds^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2$ spherical polars

Let's do an explicit example with $g_{\mu\nu}$.

Suppose we started with Minkowski spacetime with $ds^2 = -c^2 dt^2 + (dx^1)^2 + (dx^2)^2 + (dx^3)^2$

and transformed to polar coords such that $t' = t$

$x^1 = r \cos \theta \cos \phi$

$x^2 = r \cos \theta \sin \phi$

$x^3 = r \sin \theta$

③

Then the invariant line element is

$$\begin{aligned}
 ds^2 &= -c^2 dt^2 + (dr \cos\theta \cos\varphi - r \sin\theta d\theta \cos\varphi - r \cos\theta \sin\varphi d\varphi)^2 \\
 &\quad + (dr \cos\theta \sin\varphi - r \sin\theta d\theta \sin\varphi + r \cos\theta \cos\varphi d\varphi)^2 \\
 &\quad + (dr \sin\theta + r \cos\theta d\theta)^2 \\
 &= -c^2 dt^2 + dr^2 (\cos^2\theta \cos^2\varphi + \cos^2\theta \sin^2\varphi + \sin^2\theta) \\
 &\quad + d\theta^2 (r^2 \sin^2\theta \cos^2\varphi + r^2 \sin^2\theta \sin^2\varphi + r^2 \cos^2\theta) \\
 &\quad + d\varphi^2 (r^2 \cos^2\theta \sin^2\varphi + r^2 \cos^2\theta \cos^2\varphi) \\
 &\quad + dr d\theta (-r \cos\theta \sin\theta \cos^2\varphi - r \cos\theta \sin\theta \sin^2\varphi + r \sin\theta \cos\theta) \\
 &\quad + d\theta dr (") \\
 &\quad + dr d\varphi (-r \cos^2\theta \cos\varphi \sin\varphi + r \cos^2\theta \sin\varphi \cos\varphi) \\
 &\quad + d\varphi dr (") \\
 &\quad + d\theta d\varphi (r^2 \sin\theta \cos\theta \cos\varphi \sin\varphi - r^2 \sin\theta \cos\theta \sin\varphi \cos\varphi) \\
 &\quad + d\varphi d\theta (") \\
 &= -c^2 dt^2 + dr^2 + r^2(d\theta^2 + \sin^2\theta d\varphi^2)
 \end{aligned}$$

You will get exactly the same answer (try it!) if you use our expression for 2-index tensors

(3.1)

$$g_{\mu'\nu'} = \Lambda^{\sigma\mu'} \Lambda^{\lambda\nu'} g_{\sigma\lambda}$$

where

(3.2)

$$\Lambda^{\sigma\mu'} = \frac{\partial x^{\sigma}}{\partial x^{\mu'}}$$

and it's usually quicker \therefore

Note: For some vector, the quantity $\partial_{\mu} V_{\nu}$ is not in general a tensor. Why not?

Consider how this transforms under $x \rightarrow x'$:

(3.3)

$$\begin{aligned}
 \partial_{\mu} V_{\nu} &\rightarrow \frac{\partial V_{\nu'}}{\partial x^{\mu'}} = \left(\frac{\partial x^{\lambda}}{\partial x^{\mu'}} \frac{\partial}{\partial x^{\lambda}} \right) (\Lambda^{\sigma\nu'} V_{\sigma}) \\
 &= \Lambda^{\lambda\mu'} (\Lambda^{\sigma\nu'} (\partial_{\lambda} V_{\sigma}) + V_{\sigma} (\partial_{\lambda} \Lambda^{\sigma\nu'}))
 \end{aligned}$$

(3.4)

$$\partial_{\mu'} V_{\nu'} = \underbrace{\Lambda^{\lambda\mu'} \Lambda^{\sigma\nu'} \partial_{\lambda} V_{\sigma}}_{\text{like a tensor}} + \underbrace{[\Lambda^{\lambda\mu'} (\partial_{\lambda} \Lambda^{\sigma\nu'})]}_{\text{oops!}} V_{\sigma}$$

watch for this later 😊

Canonical Form

The metric can, by a suitable change of coordinates, be brought to the form

$$(4.0) \quad (g_{\mu\nu}) = \text{diag}(-1, +1, +1, +1).$$

This has "Lorentzian" signature, whereas our old friend δ_{ij} from \mathbb{R}^3 has "Euclidean" signature.

Locally Inertial Coords

At any particular point p , you can choose a reference frame in which

$$\partial_{\hat{\sigma}}^{\hat{\alpha}} g_{\hat{\mu}\hat{\nu}} \Big|_p = 0$$

BUT this cannot hold beyond first derivatives. We can do this by looking at a Taylor series expansion for the locally inertial coords (call them \hat{x}^M) in terms of the regular ones; choosing $\hat{x}^M|_p = x^M|_p$ for

$$(4.1) \quad \text{simplicity and expanding in a Taylor series} \\ x^M = \left(\frac{\partial x^M}{\partial \hat{x}^{\hat{\nu}}} \right) \Big|_p \hat{x}^{\hat{\nu}} + \text{higher-order terms} \\ \uparrow (4 \times 4 = 16 \text{ independent components})$$

We also know that $g_{\hat{\mu}\hat{\nu}} = \frac{\partial x^{\lambda}}{\partial \hat{x}^{\hat{\mu}}} \frac{\partial x^{\sigma}}{\partial \hat{x}^{\hat{\nu}}} g_{\lambda\sigma}$.

$$\text{So } g_{\hat{\mu}\hat{\nu}}(\hat{x}) \Big|_p$$

$$(4.2) \quad = g_{\hat{\mu}\hat{\nu}} \Big|_p + \frac{\partial g_{\hat{\mu}\hat{\nu}}}{\partial \hat{x}^{\hat{\beta}}} \Big|_p \hat{x}^{\hat{\beta}} + \mathcal{O}(\hat{x}^2) \\ = \left(\frac{\partial x^{\lambda}}{\partial \hat{x}^{\hat{\mu}}} \frac{\partial x^{\sigma}}{\partial \hat{x}^{\hat{\nu}}} g_{\lambda\sigma} \right) \Big|_p + \left(\frac{\partial}{\partial \hat{x}^{\hat{\beta}}} \left(\frac{\partial x^{\lambda}}{\partial \hat{x}^{\hat{\mu}}} \frac{\partial x^{\sigma}}{\partial \hat{x}^{\hat{\nu}}} \right) g_{\lambda\sigma} + \left(\frac{\partial x^{\lambda}}{\partial \hat{x}^{\hat{\mu}}} \frac{\partial x^{\sigma}}{\partial \hat{x}^{\hat{\nu}}} \frac{\partial}{\partial \hat{x}^{\hat{\beta}}} g_{\lambda\sigma} \right) \right) \Big|_p \hat{x}^{\hat{\beta}} + \dots$$

Let's compare $\mathcal{O}(1)$ and $\mathcal{O}(\hat{x})$ terms here. We get two equations (to this next-to-lowest order)

$$(5.1) \quad (a) \quad g^{\hat{\mu}\hat{\nu}}|_p = \left(\frac{\partial x^\lambda}{\partial x^{\hat{\mu}}} \frac{\partial x^\sigma}{\partial x^{\hat{\nu}}} g_{\lambda\sigma} \right)|_p \quad \text{and}$$

$$(5.2) \quad (b) \quad \left(\partial_{\hat{\beta}} g^{\hat{\mu}\hat{\nu}} \right)|_p = \left(\partial_{\hat{\beta}} \left(\frac{\partial x^\lambda}{\partial x^{\hat{\mu}}} \frac{\partial x^\sigma}{\partial x^{\hat{\nu}}} \right) g_{\lambda\sigma} + \frac{\partial x^\lambda}{\partial x^{\hat{\mu}}} \frac{\partial x^\sigma}{\partial x^{\hat{\nu}}} \partial_{\hat{\beta}} g_{\lambda\sigma} \right)|_p$$

▷ For (a), having 16 functions (see (4.1)) is enough to specify $\frac{1}{2!}(4 \times 5) = 10$ independent metric components.

The 6 left over are the 6 parameters of the Lorentz group in the locally inertial frame! 😊
(3 rotations & 3 boosts.)

▷ For (b), for 2nd term, we have 4 derivatives of 10 cpts, i.e. 40 independent bits to worry about. Also, for 1st term,
 $\partial_{\hat{\beta}} (\partial_{\hat{\mu}} x^\lambda) (\partial_{\hat{\nu}} x^\sigma) = (\partial_{\hat{\beta}} \partial_{\hat{\mu}} x^\lambda) (\partial_{\hat{\nu}} x^\sigma) + (\partial_{\hat{\mu}} x^\lambda) (\partial_{\hat{\beta}} \partial_{\hat{\nu}} x^\sigma)$

Notice that $\frac{\partial^2 x^\lambda}{\partial x^{\hat{\beta}} \partial x^{\hat{\mu}}}$ is symmetric in $(\hat{\beta} \leftrightarrow \hat{\mu})$ so it also has 40 cpts.

So by adjusting \uparrow as necessary, we can make $\partial_{\hat{\beta}} g^{\hat{\mu}\hat{\nu}} = 0$ at p (ONLY!), as required.

Pattern: at higher orders in Taylor expansion, there are not enough independent components of 3rd derivative of x to adjust 2nd derivs of g to zero.
 [This is where a new construct, called the Riemann curvature tensor, which we will meet later, comes in.]
 → See Carroll p.75 for the proof.

Question:

If special relativity "works" only locally, what happens in curved space-time to our notions of causality?

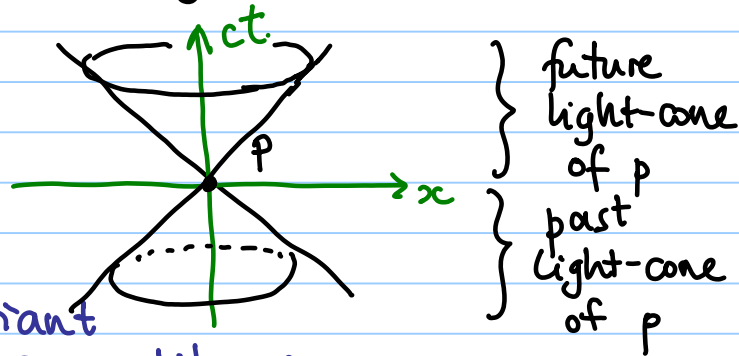
Causality

Recall that in lecture of 15 Sep, I introduced the SR concept of the light-cone. We can use the same idea in GR, but it will depend on our point p .

The future light-cone of p in SR is all the points q that can be reached from p via light-ray. Similarly for the past light-cone.

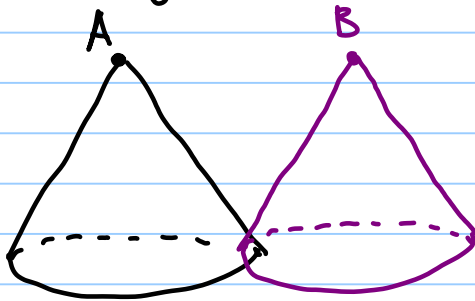
Note: "points" in space-time are also called "events".

SR



Even in SR, there is no invariant notion of simultaneity. But Causality is well-defined: if p could have caused q (e.g. by sending a signal using $|v| \leq c$ particle) then q could not have caused p (without violating the law that $|v| \leq c$.)

We can also consider 2 points in Minkowski space, A and B , and ask if they could have been caused by the same event p . We figure this out by looking at their past light-cones:



Going back far enough, the "past light-cones" overlap.

This is true in Minkowski space for any A & B (!)

Such points are said to be "in causal contact".

Let's do a curved-space example.

(7.1) Consider $ds^2 = -c^2 dt^2 + t dx^3^2$

This spacetime doesn't make sense for $t \leq 0$; in particular, physics is singular at $t=0$ (roughly, \because proper lengths in all directions go to zero there.). So restrict $0 < t < \infty$.

Let a light-ray go along x^3 direction (w.l.o.g.) Then for path $x^M(\lambda)$ of light-ray, we have

$ds^2 = 0$ (light-like interval)
 $= -c^2 dt^2 + t(dx^3)^2 + 0 + 0$

and for this path $\frac{dx^M}{d\lambda}$ is a tangent vector so that

$(\frac{ds}{d\lambda})^2 = 0 = -c^2(\frac{dt}{d\lambda})^2 + t(\frac{dx^3}{d\lambda})^2 \Rightarrow \frac{dx^3}{dt} = \pm \frac{c}{\sqrt{t}} \rightarrow \pm \infty @ t \rightarrow 0$

(7.2) c.f. Minkowski-spacetime answer $\frac{dx^3}{dt} = \pm c$.

\Rightarrow light-cones are not generally at 45° on spacetime diagram.

(7.3) We can also integrate: $x^3(t) - x^3_0 = \pm 2c(\sqrt{t} - \sqrt{t_0})$
Let's follow 2 particles; assume same clock (OK by (7.1))

i.e. $x^3_{(j)} = x^3_{0(j)} \pm 2c\sqrt{t}$ $j=1,2$

(7.4) $ct_{(j)} = \frac{1}{4} (x_{(j)} - x_{0(j)})^2$ $t > 0$
Parabolas



- Light-cones degenerate @ $t \rightarrow 0$
- These 2 points are not causally connected (c.f. Big Bang!)